

Frequency divider

FT 1D-1D

HTL, TTL / RS422



The frequency divider FT 1D-1D is intended for the error-free division of frequencies or pulses from conventional encoders, sensors or other incremental measuring systems.

Four readily accessible DIL switches allow programming division ratios from 1:1 up to 1:4096 and the desired representation of the direction of rotation. A separately adjustable divider is available for the zero pulse.

The module can be easily and conveniently mounted in a cabinet on a standard DIN rail.









Limit frequency

mount

Features

- Level conversion from HTL single ended, RS422 to HTL differential and vice-versa.
- · Limit frequency 1 MHz
- Division of double-track (A, B, 90°) pulses with adjustable ratio from 1: 1 to 1: 4096.
- Division of the Z pulse with adjustable ratio from 1:1 to 1:256.
- · Push-pull outputs for direct PLC control.
- External input for zeroing the A/B/Z divider (defined start / stop).
- Independent second Z divider adjustable.
- · Z pulse division ratio adjustable.

Benefit

- Frequency reduction for slow controls.
- · External scaling for controls.
- Active signal adaptation for High/Low level.
- · Adjustable zero pulse for specific applications

Order no.

Frequency divider

8.FT.1D-1D

 ${\it Scope of delivery}$

- Frequency divider
- Manual



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Technical data

Electrical characteristics										
Power supply			9 30 V DC (residual ripple \leq 10 % at 24 V DC)							
Power consumption (encoder supply wit		at 9 V at 30 V	approx. 40 mA approx. 30 mA							
Type of connection			screw terminal, 1.5 mm²							
Encoder supply		t voltage t current nnection	$+5.5$ V DC / ±5 % max. 130 mA screw terminal, 1.5 mm ²							

Mechanical characteristics								
Material	housing	plastic						
Mounting		35 mm DIN rail (acc. to EN 60715)						
Dimensions (W x H x D)		22.5 x 102 x 102 mm [0.89 x 4.02 x 4.02"]						
Protection		IP20						
Weight		approx. 100 g [3.53 oz]						
Working temperature		0 °C +60 °C [+32 °F +140 °F] non condensing						
Storage temperature		-25 °C +70 °C [-13 °F +158 °F] non condensing						
Failure rate (MTBF in years)		109,3 a continuous operation at 60 °C [140 °F]						

Approvals	
CE compliant in accordance with	
EMC Directive	2014/30/EU
RoHS Directive	2011/65/EU
UKCA compliant in accordance with	
EMC Regulations	S.I. 2016/1091
RoHS Regulations	S.I. 2012/3032

Incrementa	al input X4	
Signal level	TTL / RS422 HTL	differential voltage > 1 V LOW: 0 4 V / HIGH: 10 30 V
HTL internal	resistance	Ri ≈ 4.7 kOhm
Tracks	TTL / RS422, symmetrical	A, /A, B, /B, 0, /0 (RS422, HTL differential) A, B, 0
Frequency	HTL differential HTL single ended TTL	max. 1 MHz (HTL differential signal > 2 V) max. 350 kHz, Level 1: Low 0 10 V, High 14 30 V Level 2: Low 0 5 V, High 9 30 V max. 350 kHz, Low 0 0.7 V, High 2.2 5 V
Type of conne	ection HTL, TTL / RS422	screw terminals, 1.5 mm²

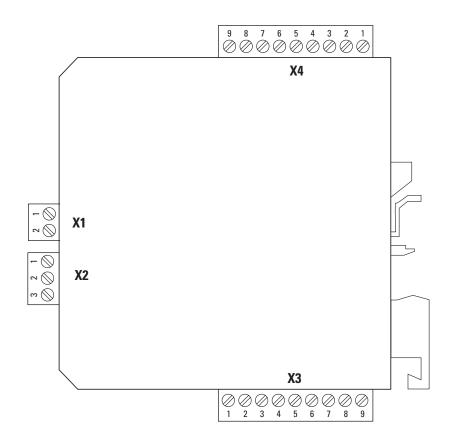
Incremen	ital output X3	
Level		8 29 V at HTL (depending on the supply voltage)
Tracks	TTL / RS422, symmetrical HTL, asymmetrical	A, /A, B, /B, 0, /0 (5 V DC) A, B, 0
Output curr	ent	max. 20 mA / Push-Pull
Type of connection		screw terminals, 1.5 mm²

Control input X2		
Level		HTL, PNP Low 0 5 V, High 9 30 V
Tracks	frequency response time	max. 20 kHz 50 us
Input current		max. 3 mA
Type of connection		screw terminals, 1.5 mm²



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Terminal assignment



Interface	Function	Screw terminals, 2-pin				
Connection X1	Davis aventu	Signal:	0 V	+V		
	Power supply	Pin:	1	2		

Interface	Function	Screw terminals, 3-pi	n		
Connection X2	Control input	Signal:	GND	Contr. 1	Contr. 2
		Pin:	1	2	3

Interface	Function	Screw terminals, 9-pin									
Connection X3	Incremental output	Signal:	ERR	GND	А	Ā	В	B	0	ō	GND
		Pin:	1	2	3	4	5	6	7	8	9

Interface	Function	Screw terminals, 9-pin									
Connection X4	Incremental input	Signal:	GND	0	0	B	В	Ā	Α	GND	+5 V out
		Pin:	1	2	3	4	5	6	7	8	9

+V: Power supply

0 V: Encoder power supply ground GND (0 V)

Contr. 1 /2: Control inputs

GND: Frequency divider power supply ground (0V)

Error : Error output

 $\begin{array}{lll} A,\,\overline{A}: & & \text{Incremental output channel A (Cosine)} \\ B,\,\overline{B}: & & \text{Incremental output channel B (Sine)} \end{array}$

 $0, \overline{0}$: Reference signal

3



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Dimensions

Dimensions in mm [inch]

